SYLLABUS

1. Data about the program of study

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1.1	Institution	The Technical University of Cluj-Napoca
1.2	Faculty	Automotive Engineering, Mechatronics and Mechanics
1.3	Department	Automotive Engineering and Transportation
1.4	Field of study	Automotive Engineering
1.5	Cycle of study	Master's in Science
1.6	Program of study (Qualification	Tehnici Avansate în Ingineria Autovehiculelor (Advanced
1.6	Program of study/Qualification	Techniques in Automotive Engineering) - în limba engleză
1.7	Form of education	Full time
1.8	Subject code	13.00

2. Data about the subject

2.1	Subject name			Hardware and So	ftware in	n the Loop		
2.2	Subject area			Automotive Engir	neering			
2.3	Course responsible/lecturer				Associate Profess calin.iclodean@a			
2.4	Teachers in charge of seminars				Associate Profess calin.iclodean@a			
2.5	2.5 Year of study II 2.6 Semester 3			2.7 Assessment	Е	2.8 Subject category	DA/DI	

3. Estimated total time

3.1 Nu	mber of hours per week	4	3.2 of w	hich, course:	2	3.3 applications:	2
3.4 To ⁻	tal hours in the curriculum	100	3.5 of w	hich, course:	28	3.6 applications:	28
Individual study							hours
Manu	al, lecture material and notes, b	oibliogra	phy				16
Supplementary study in the library, online and in the field						16	
Preparation for seminars/laboratory works, homework, reports, portfolios, essays					10		
Tutoring					-		
Exams and tests					2		
Other activities						-	
3.7	3.7 Total hours of individual study 44						
3.8	3.8 Total hours per semester 100						
3.9	Number of credit points		4				

4. Pre-requisites (where appropriate)

4.1	Curriculum	-
4.2	Competence	General knowledge in the fields of automotive, electronics and computer science.

5. Requirements (where appropriate)

5.1	For the course	-
5.2	For the applications	Attending (100% attendance) and performing (promoting) the activities from the laboratory applications condition the admission to the final form of evaluation of the discipline.

6. Specific competences

	Ability to describe, explain and demonstrate the operation of the main command and control systems and equipment in the field of automobile construction.
le es	Knowledge of the functional role of the main command and control systems and equipment in
ů ů	the field of car construction.
ssic	Knowledge of some typologies of architectures for the communication networks used in the
ofes	construction of vehicles and the deepening of the main physical and virtual models used in the
Professional competences	development and validation of these communication networks.
- 0	Knowledge of possible faults and the way, respectively of the repair procedures.
	Knowledge of the advantages of using command and control systems in the construction of
	vehicles developed in physical and virtual environments.
	Oral and written communication skills in the mother tongue / foreign language.
es	Use of information and communication technology.
enc	Execution of professional tasks according to the specified requirements following a pre-
lete	established work plan under qualified guidance.
du	Completion of homework and projects imposed on time and at a high-quality standard.
Cross competences	Integration within a working group, assuming specific roles and achieving good communication
oss	within the team.
C	Achieving personal and professional development, efficiently using own resources and modern
	study tools.

7. Discipline objectives (as results from the key competences gained)

7.1	General objective	Development of specific skills in the field of command-and-control systems and equipment in the field of automobile construction in support of professional training.
7.2	Specific objectives	Assessment and analysis of requirements for new technologies integrated in vehicles in order to implement advanced command and control systems.

8. Contents

8.1. Lecture (Syllabus)	Methods	Notes
1. In-Vehicles ECU (Electronic Control Unit).		2 hours
2. Virtual ECU for Powertrain Domain.		2 hours
3. Virtual ECU for Chassis and Safety Domain.		2 hours
4. Virtual ECU for Body and Confort Domain.		2 hours
5. Virtual ECU for Infotainment Domain.	Exposure,	2 hours
6. Virtual ECU for Telematic Domain.	conversation,	2 hours
7. Embedded System development based on the "V" Model.	exemplification,	2 hours
8. Model-in-the-Loop (MiL) model development methodology.	orientation, etc.	2 hours
9. Software-in-the-Loop (SiL) model development methodology.	Use of technical	2 hours
10. Processor-in-the-Loop (PiL) model development methodology.	and visual means.	2 hours
11. Hardware-in-the-Loop (HiL) model development methodology.		2 hours
12. AUTOSAR Classic Architecture.		2 hours
13. AUTOSAR Adaptive Architecture.		2 hours
14. AUTOSAR Application Interface.		2 hours
8.2. Applications/Seminars	Methods	Notes
1. XiL development methods in simulation applications (1).	_ ·	2 hours
2. XiL development methods in simulation applications (2).	Exercices,	2 hours
3. Defining a virtual model based on a real model (1).	conversations,	2 hours
4. Defining a virtual model based on a real model (2).	description, modeling, etc. Use of technical	2 hours
5. Defining a virtual model based on a real model (3).		2 hours
6. Defining a virtual model based on a real model (4).		2 hours

7. XiL development: Virtual ECU modeling (1).	and visual	2 hours		
8. XiL development: Virtual ECU modeling (2).	means.	2 hours		
9. XiL development: Virtual ECU modeling (3).		2 hours		
10. Testing and optimizing Virtual ECU parameters (1).		2 hours		
11. Testing and optimizing Virtual ECU parameters (2).		2 hours		
12. Testing and optimizing Virtual ECU parameters (3).		2 hours		
13. Testing and optimizing Virtual ECU parameters.		2 hours		
14. Analysis and interpretation of simulation results.		2 hours		
Bibliography				
1. Bosch Automotive Electrics and Automotive Electronics Systems	and Components (<u>lin</u>	<mark>.k</mark>).		
2. Bosch Automotive Mechatronics, Automotive Networking, Electr	onics (<mark>link</mark>).			
3. Bosch Diesel Engine Management, Systems and Components (lin	<u>k</u>).			
4. Bosch Gasoline Engine Management Systems and Components (<u>ink</u>).			
5. Bosch Fundamentals of Automotive and Engine Technology, Stan	dard Drives (<u>link</u>).			
6. Bosch CAN Specification version 2.0 (<u>download link</u>).				
7. Bosch CAN FD Specification version 1.0 (download link).				
8. Grzemba MOST The Automotive Multimedia Network (download	<u>l link</u>).			
9. Iclodean Metode de Simulare a Sistemelor de Propulsie prin Aplie	cații Numerice (<mark>dowr</mark>	<u>nload link)</u> .		
10. Iclodean Rețele de Comunicație pentru Autovehicule (<u>download link</u>).				
11. Iclodean Interconectarea sistemelor virtuale de control pentr	u autovehicule (<u>dow</u>	<u>nload link</u>).		
12. Kozierok Automotive Ethernet: The Definitive Guide (download				
13. Mariașiu Aplicații Numerice în Simularea Proceselor Motoarelor	⁻ cu Ardere Internă (<mark>c</mark>	<u>download link</u>).		
14. Mariașiu Managementul Motoarelor cu Ardere Internă (downlo				
15. Burnete Motoare cu Ardere Internă Procese și Management Mo				
16. Paret FlexRay and its Applications: Real Time Multiplexed Netwo				
17. Varga Electric and Plug-In Hybrid Vehicles Advanced Simulation				
18. Varga Electric and Hybrid Buses for Urban Transport Energy Effi	ciency Strategies (<u>lin</u>	<u>k</u>).		
19. Iclodean Autonomous Vehicles for Public Transportation (<u>link</u>).				
20. Varga Simulation in the Loop of Electric Vehicles (download link				
21. FlexRay Communications System Protocol Specification version).		
22. Freescale Automotive Solutions Setting the Pace for Innovation				
23. Paret Multiplexed Networks for Embedded Systems: CAN, LIN, F	lexRay, Safe-by-Wire	e (<u>link</u>).		
24. LIN Specification Package revision 2.2A (<u>download link</u>).				
25. MatLab & Simulink Vehicle Network Toolbox version R2021a (d	ownload link).			
26. AUTOSAR Standard Classic Platform (<u>download link</u>).				
27. AUTOSAR Standard Adaptive Platform (<u>download link</u>).				
28. AUTOSAR Application Interface (<u>download link</u>).				

9. Bridging course contents with the expectations of the representatives of the community, professional associations, and employers in the field

In the training of skills, the options of employers recommended to higher education institutions for the training of graduates are taken into account (ability to use time efficiently, ability to work in a team, ability to learn quickly, ability to coordinate teams, new opportunities in the interest company, the ability to use the computer and the Internet, the ability to adapt to new situations, etc.) and the priorities recommended by employers in training graduates (creativity and ability to innovate, the ability to negotiate, the ability to critically analyze, the ability to learn quickly, knowledge from other fields). The content of the discipline is in accordance with the study materials and methods that are used by Bosch Romania Company. The content of the discipline is in the country and abroad.

10. Evaluation

Activity type	10.1 Assessment criteria	10.2 Assessment methods	10.3 Weight in the final grade		
10.4 Course	The degree of assimilation of the notions presented during the course. Correctness of acquired knowledge.	Written evaluation.	60%		
10.5 Applications	Ability to operate with assimilated knowledge.	Checking applications.	40%		
10.6 Minimum standard of performance: final grade 5.					

Date of filling in:		Title Surname Name	Signature
07.03.2023	Teechers in	Associate Professor PhD Iclodean Călin	
		Associate Professor PhD Iclodean Călin	

Date of approval in the department 20.04.2023

Date of approval in the faculty

Dean Prof.dr.ing. Filip Nicolae

Head of department

Prof.dr.ing. Barabás István

____11.10.2023_____